

LAST WEEK, WE TALKED ABOUT INVERSES OF  $2 \times 2$  MATRICES. LET'S GENERALIZE!  
 IF WE TAKE OUR  $n \times n$  MATRIX, THEN AUGMENT WITH  $I$ , THE  $n \times n$  IDENTITY.  
 THEN WE CAN USE GAUSS-JORDAN ELIMINATION. ONCE THE LHS MATRIX  
 IS  $I$ , THE RHS WILL BE THE INVERSE.

eg/

$$[A|I] \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 2 & 3 & 0 & | & 0 & 1 & 0 \\ 0 & -2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2: R_2 - 2R_1} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 5 & -2 & | & -2 & 1 & 0 \\ 0 & -2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & -2 & 1 & | & 0 & 0 & 1 \\ 0 & 5 & -2 & | & -2 & 1 & 0 \end{bmatrix}$$

$$\xrightarrow{R_2: R_2 / -2} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & -\frac{1}{2} & | & 0 & 0 & -\frac{1}{2} \\ 0 & 5 & -2 & | & -2 & 1 & 0 \end{bmatrix} \xrightarrow{R_3: R_3 - 5R_2} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & -\frac{1}{2} & | & 0 & 0 & -\frac{1}{2} \\ 0 & 0 & -\frac{5}{2} & | & -2 & 1 & \frac{5}{2} \end{bmatrix}$$

$$\xrightarrow{R_2: R_2 + R_3} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & -2 & 1 & 2 \\ 0 & 0 & \frac{1}{2} & | & -2 & 1 & \frac{5}{2} \end{bmatrix} \xrightarrow{R_3: R_3 \times 2} \begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & -2 & 1 & 2 \\ 0 & 0 & 1 & | & -4 & 2 & 5 \end{bmatrix}$$

$$\xrightarrow{R_1: R_1 + R_2} \begin{bmatrix} 1 & 0 & 1 & | & -1 & 1 & 2 \\ 0 & 1 & 0 & | & -2 & 1 & 2 \\ 0 & 0 & 1 & | & -4 & 2 & 5 \end{bmatrix} \xrightarrow{R_1: R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 & | & 3 & -1 & -3 \\ 0 & 1 & 0 & | & -2 & 1 & 2 \\ 0 & 0 & 1 & | & -4 & 2 & 5 \end{bmatrix} = [I|A^{-1}]$$

EVERY ELEMENTARY ROW OPERATION WE USE IN GAUSSIAN ELIMINATION (OR GAUSS-JORDAN) CAN BE REPRESENTED AS A SINGLE MATRIX. APPLYING THE OPERATION IS THE SAME AS LEFT-MULTIPLYING BY THE ELEMENTARY MATRIX

egs/

$R_1: R_1 / 2$        $R_2 \leftrightarrow R_3$        $R_3: R_3 - 2R_1$

$$E = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$

SOME SPECIAL MATRICES:

DIAGONAL MATRICES HAVE NUMBERS ALONG MAIN DIAGONAL, ZEROS EVERYWHERE ELSE  
UPPER (LOWER) TRIANGULAR MATRICES HAVE NUMBERS ON AND ABOVE (BELOW) THE  
MAIN DIAGONAL AND ZEROS EVERYWHERE ELSE.  
SYMMETRIC MATRICES ARE ANY MATRICES WHERE  $A^T = A$ .

NOW WE WILL SHIFT TO TALK ABOUT A NEW CONCEPT CALLED THE DETERMINANT.  
 THE DETERMINANT IS RELATED TO AREA/VOLUME. I'LL TALK MORE ABOUT THIS LATER!

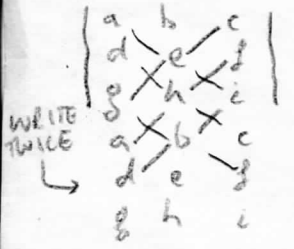
$2 \times 2$  DETERMINANT:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc \quad (\text{LOOKS FAMILIAR!})$$

$3 \times 3$  DETERMINANT:

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = aei + bfg + cdh - cef - bdi - afh$$

TRICK FOR  $3 \times 3$ : ADD ALONG DIAGONALS, SUBTRACT ALONG ANTIDIAGONALS:



NOTE: THE DETERMINANT IS A NUMBER!

$$\text{eg/ } \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 1 \cdot 4 - 2 \cdot 3 = 4 - 6 = -2$$

$$\text{eg/ } \begin{vmatrix} 1 & 2 \\ 3 & 6 \end{vmatrix} = 1 \cdot 6 - 2 \cdot 3 = 6 - 6 = 0 \quad (\text{BECAUSE } \det(A) = 0 \Rightarrow A \text{ IS NOT INVERTIBLE})$$

$$\text{eg/ } \begin{vmatrix} 1 & 0 & 2 \\ 3 & 4 & 5 \\ 2 & -1 & -4 \end{vmatrix} = -16 + 0 - 6 - 16 + 5 - 0 = -33$$

WE CANNOT GENERALLY FIND THE DETERMINANT EASILY FOR  $n \times n$   $n \geq 4$ , NO TRICKS!  
BUT WE CAN USE COFACTOR EXPANSION.

LET'S SHOW WITH AN EXAMPLE:

$$\begin{aligned} \text{eg/ } \begin{vmatrix} 1 & 0 & 2 \\ 3 & 4 & 5 \\ 2 & -1 & -4 \end{vmatrix} &= (-1)^{1+1} (1) \begin{vmatrix} 4 & 5 \\ -1 & -4 \end{vmatrix} + (-1)^{1+3} (2) \begin{vmatrix} 3 & 4 \\ 2 & -1 \end{vmatrix} \\ &= \begin{vmatrix} 4 & 5 \\ -1 & -4 \end{vmatrix} + 2 \begin{vmatrix} 3 & 4 \\ 2 & -1 \end{vmatrix} \\ &= -21 - 22 = -33 \end{aligned}$$